Inría

•<u>Context</u>: Signals coming from diverse sensory inputs for the same given source are heterogenous and often have overlapping information. Presheaves are one way to model such *compositional* signals and their interactions [1].

Abstract

• Problem: perform model selection when only 'partial' objectives pertaining to different parts of the data are accessible, compatible with model selection over the unknown source

•Contribution: we propose an objective function and introduce efficient message-passing algorithms to find its critical points.

Compositionality: What and Why? •What is compositionality?

"The ability to determine properties of the whole [system] from properties of the parts together with the way in which the parts are put together." [2]

•Why consider compositional 'signals'?

When multiple 'partial' information on signal (e.g. from sensors) and need to synthesize information to make a decision.

Example in the following situations:

→ Multi-modal integration \rightarrow Heterogeneity in signal [3] \rightarrow Data fusion [1] \rightarrow Incomplete/partial information \rightarrow Incompatibilities \rightarrow Genericity, high modeling power

Presheaves as spaces of signals –

•**Signal:** a collection of 'partial' signals structured hierarchically; their interactions define 'embeddings' into common spaces.

•Modeled as: a section of a presheaf over a hierarchy/partially ordered set (\mathscr{A}, \leq) (e.g. inclusions if $b \subseteq a$ and $c \subseteq b$ then $c \subseteq a$).

Definition 2: Presheaf *F* **over a (finite) poset:**

- 1. Sends element $a \in \mathcal{A}$ to a (finite vector) space F(a)
- 2. Relation $b \le a$ to linear map between spaces

$$F_a^b: F(b) \to F(a)$$

3. Respects Transitivity: $F_a^b \circ F_b^c = F_a^c$

F(b)

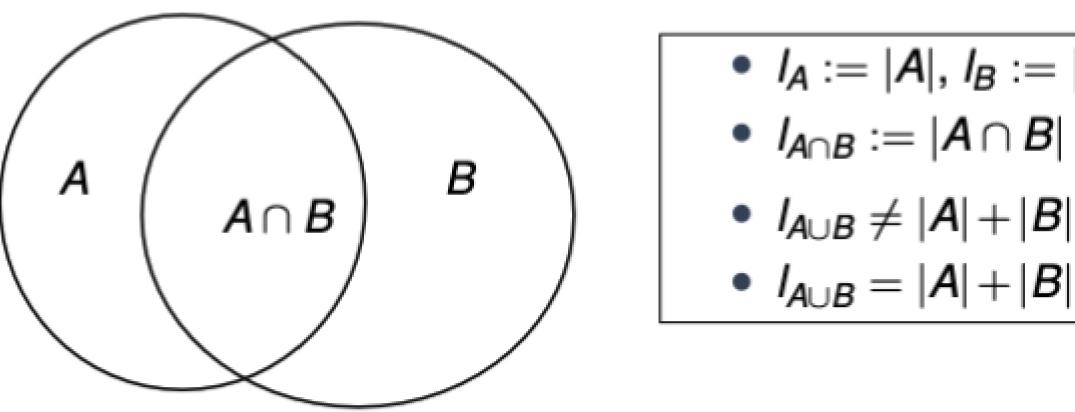
Optimization over presheaves Grégoire Sergeant-Perthuis¹



F_c $c \le b \le a$

Setting the (optimization) problem

- A partial signal ($v_a \in F(a)$) coming from a source s; a compositional signal $\rightsquigarrow (v_a, a \in \mathscr{A})$
- A collection of partial cost functions $l_a: F(a) \to \mathbb{R}$
- A reconstruction of $s \rightsquigarrow$ for all $b \le a$, $F_b^a(v_a) = v_b$
- **But** when overlappings might count cost several times !



Optimization problem

• The Möbius function of a *finite* A allows to generalize inclusionexclusion formulas; denoted $\mu: \mathscr{A} \times \mathscr{A} \to \mathbb{Z}$

Definition 3: Combinatorial loss over a presheaf -

For any $v := (v_a \in F(a), a \in \mathscr{A}),$

 $l_F(v) := \sum_{a \in \mathscr{A}} c(a) l_a(x_a)$ where, $c(a) = \sum_{b \ge a} \mu(b, a)$

• **Optimization problem:** Minimize $l_F(v)$ under the constraint (C) that for all $b \le a$, $F_b^a(v_a) = v_b$

Parametrizing the constraints

• Denote the linear map from $\bigoplus_{a \in \mathscr{A}} F(a)$ to $\bigoplus_{a,b \in \mathscr{A}} F(b)$,

 $\forall b \le a \quad \delta_F(v)(a,b) := F_b^a(v_a) - v_b$

• The constraint (C) is equivalent to $\delta(v) = 0$

• The Lagrange multipliers are in the image of d := δ^*

Proposition: Characterization of critical points —

A $v = (v_a, a \in \mathscr{A})$ satisfying (C) is a critical point of l_F (on (C)) iff $\exists m$ such that for any $a \in \mathcal{A}$,

 $d_v l_a = \sum F_b^{a*} dm(a) (= \zeta_{F^*} dm)$

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• $I_A := |A|, I_B := |B|$ • $I_{A\cup B} \neq |A| + |B| + |A \cap B|$ • $I_{A\cup B} = |A| + |B| - |A \cap B|$

> $a \ge b$ (1)

(2)

Message passing algorithm

• Assume that the following condition holds:

$$\forall a \in \mathscr{A} \forall v_a \in F(a), y_a \in F(a)^*$$

- Update rule
- $m(t+1) m(t) = \delta_F g \zeta_{F^*} d_F m(t)$
- When F_h^{a*} is encoded by $F_h^{a\top}: F(b) \to F(a)$ the transpose of F_h^a :

Algorithm 1 Message passage algorithm for combinatorial loss Initialization $(m^0_{a \to b} \in F(b), b, a \in \mathscr{A} \text{ s.t. } b \leq a)$, poset \mathscr{A} , a presheaf F; while True do

for $a \in \mathscr{A}$ do $n_a \leftarrow \sum_{b:b < a} \sum_{c:c < b} F_c^{a \top} m_{b \to c} - \sum_{b:b < a} \sum_{c:c > b} F_b^{a \top} m_{c \to b}$

for $b \in \mathscr{A}$ do

if $b \leq a$ then $m_{a \to b} \leftarrow m_{a \to b} = m_{a \to b} + F_b^a g_a(n(a)) - g_b(n(b))$

Algorithm 'solves' optimization -

Theorem: Fix points of algorithm are critical points —

Roots of $\delta_F g \zeta_{F^*} d_F$ are in correspondence with critical points of the combinatorial loss l_F on the constrained space defined by (C), i.e.

 $\delta_F g \zeta_{F^*} \mathsf{d}_F \overline{m} = 0 \iff \exists v_* \in (C), d_{v^*} l_F|_{(C)} = 0 \& v_* = g \zeta_{F^*} \mathsf{d}_F \overline{m}$

References

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Paper



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 $d_{v_a}l_a = y_a \iff g_a d_{v_a}l_a = y_a$

Based on: 'Regionalized Optimization'[4]